



**12<sup>th</sup> IEEE International  
Conference**  
[www.aict.info/2018](http://www.aict.info/2018)



**AICET**  
INTERNATIONAL CONFERENCE

**APPLICATION  
OF INFORMATION  
AND COMMUNICATION  
TECHNOLOGIES - AICT2018**

17-19 October 2018, Almaty, Kazakhstan

**CONFERENCE  
PROCEEDINGS**

*17-19 October 2018, Almaty, Kazakhstan*

*[www.aict.info/2018](http://www.aict.info/2018)*



## CONFERENCE PROCEEDINGS

2018 IEEE 12<sup>th</sup> International Conference on Application of Information and Communication Technologies (AICT)

Copyright © 2018 by the Institute of Electrical and Electronics Engineers, Inc. All rights reserved.

### Copyright and Reprint Permission

Abstracting is permitted with credit to the source. Libraries are permitted to photocopy beyond the limit of U.S. copyright law, for private use of patrons, those articles in this volume that carry a code at the bottom of the first page, provided that the per-copy fee indicated in the code is paid through the Copyright Clearance Center, 222 Rosewood Drive, Danvers, MA 01923.

Other copying, reprint, or reproduction requests should be addressed to IEEE Copyrights Manager, IEEE Service Center, 445 Hoes Lane, P.O. Box 1331, Piscataway, NJ 08855-1331.

IEEE Catalog Number: CFP1856H-PRT

ISBN: 978-1-5386-6467-4

Additional copies of this publication are available from  
Curran Associates, Inc.

57 Morehouse Lane  
Red Hook, NY 12571 USA

+1 845 758 0400

+1 845 758 2633 (FAX)

email: curran@proceedings.com

© Designed by the AICT2018 Publication Team, 2018.

IEEE Catalog Number: CFP1856H-PRT

ISBN: 978-1-5386-6467-4

# Solving the Reverse Problems of Pharmacokinetics for a Linear Two-Compartment Model with Absorption

Baydaulet A. Urmashhev, Aisulu T. Tursynbay, Almas N. Temirbekov, Aidana B. Amantayeva

Kazakh National University named after al-Farabi, Almaty, Kazakhstan

baydaulet.urmashev@kaznu.kz, tursynbay\_a@mail.ru, almas.temirbekov@kaznu.kz, aman.aydana@gmail.com

**Abstract** — A new method is proposed for revealing the nonuniqueness of the solution of the inverse problem. The existence of three solutions of this equation is analytically proved and an algorithm for their finding is presented. The obtained results indicate the ambiguity of solutions of inverse problems and the obtained sets of parameters of the corresponding numerical methods for solving inverse problems of pharmacokinetics require additional conditions for determining the necessary set of pharmacokinetic parameters.

**Keywords** — Pharmacokinetics; nonuniqueness of the solution inverse problems; numerical methods; linear two-compartment model with absorption;

## I. INTRODUCTION

The theoretical proof of the nonuniqueness of the solution is confirmed by numerical calculations. To solve the inverse problem of models of pharmacokinetics, there were used several numerical methods that satisfy the criterion of the method of least squares. The software complex pharmacokinetics 2.0 was developed. High performance will be provided by developing algorithms to solve the main problems in Fortran and C programming languages. These defacto programming languages are the fastest for implementation of complex mathematical calculations. The applications developed in these programming languages will be called through the architecture of micro services. Using the example of a computational experiment, the software complex was used for finding the pharmacokinetic parameters for a linear two-chamber pharmacokinetics model with absorption.

## II. RELATED WORK

Previously, in the works [1, 2] we studied the kinetics of the reaction system (1), (2). It was shown that the equation of the dependence of concentration on time for component B has more than one solution. The result of this work is a rigorous analytical substantiation of the number of solutions of this equation and the identification of the conditions for the realization of each of them.

The chemical kinetics of processes (1-2) is described by the solution of the Cauchy problem for a system of linear ordinary differential equations (3-10):



$$\frac{dC_1}{dt} = -k_1 C_1 \quad (3)$$

$$\frac{dC_2}{dt} = k_1 C_1 - (k_2 C_2 + k_3 C_2) + k_4 C_4 \quad (4)$$

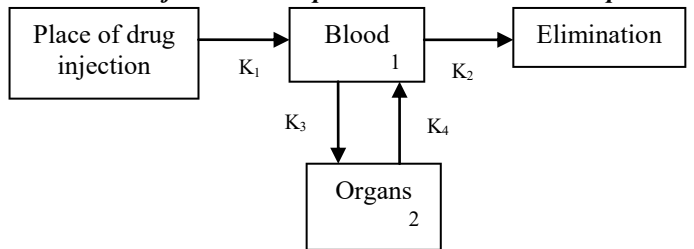
$$\frac{dC_3}{dt} = k_2 C_2 \quad (5)$$

$$\frac{dC_4}{dt} = k_3 C_2 - k_4 C_4 \quad (6)$$

$$C_1(0) = C_0, C_2(0) = 0, C_3(0) = 0, C_4(0) = 0, \quad (7-10)$$

here  $C_i(t)$  - concentration of components **A**, **B**, **C**, **D** at the time moment  $t$ ,  $k_i$  - rate constants of the individual reaction stages 1 and 2.

*Scheme of the two-compartment model with absorption*



On the basis of differential equations (3-6) with the above-mentioned initial conditions, the desired dependence  $C_2(t) = f(t)$  - the dynamics of the change in the concentration of component **B** can be represented in the form of equation 11 [3, 4].

$$C_2(t) = A_1 e^{-\lambda_1 t} + A_2 e^{-\lambda_2 t} - A_3 e^{-k_1 t}, \quad (11)$$

where:

$$A_1 = \frac{k_1(\lambda_1 - k_4) \cdot C_0}{(\lambda_1 - \lambda_2)(k_1 - \lambda_1)} \quad (12)$$

$$A_2 = \frac{k_1(\lambda_2 - k_4) C_0}{(\lambda_1 - \lambda_2)(\lambda_2 - k_1)} \quad (13)$$

$$A_3 = -(A_1 + A_2) = \frac{k_1(k_4 - k_1) C_0}{(k_1 - \lambda_1)(k_1 - \lambda_2)} \quad (14)$$

$$\lambda_{1,2} = \frac{1}{2} \cdot \left[ (k_2 + k_3 + k_4) \pm \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2 k_4} \right] \quad (15)$$

$$\lambda_1 + \lambda_2 = k_2 + k_3 + k_4, \quad \lambda_1 \lambda_2 = k_2 k_4 \quad (16-17)$$

The solution of the direct problem in this case is not difficult. In Fig.1 presented calculated values of the concentration of substance **B** for the given values of reaction rate constants  $k_i$  and its initial concentration equal to 50.

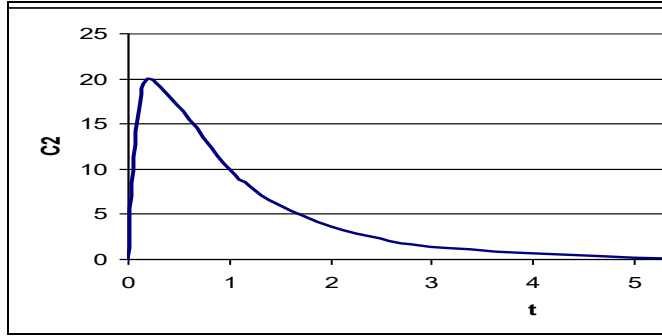


Fig. 1. Dependencies of concentration  $C_2(t)$  on time for values.

$$C_0 = 50, k_1 = 5, k_2 = 2, k_3 = 3, k_4 = 4.$$

### III. MATERIALS AND METHODS

The inverse problem is the calculation of the quantities  $k_i$  and  $C_0$  on the basis of some set of measured values  $C_{2i}$  at the time moment  $t_i$ , in comparison to the straight one, is a much more complicated problem [4]. To solve it, equation (11) is presented in the following form (18):

$$C_2^{calc}(t) = L_1 e^{-\varepsilon_1 t} + L_2 e^{-\varepsilon_2 t} + L_3 e^{-\varepsilon_3 t} \quad (18)$$

Coefficients  $L_i$  and  $\varepsilon_i$  of this equation are related as follows:

$$L_1 + L_2 + L_3 = 0, \quad (19)$$

$$\varepsilon_1 \neq \varepsilon_2 \neq \varepsilon_3, \quad (20)$$

$$\varepsilon_1 > 0, \varepsilon_2 > 0, \varepsilon_3 > 0. \quad (21)$$

Taking into account equality (19), the total number of unknowns in equation (18) decreases until 5. Values of  $L_1, L_2, \varepsilon_1, \varepsilon_2, \varepsilon_3$  were found by the method of least squares:

$$\sum_i (C_2^{exp}(t_i) - C_2^{calc}(t_i))^2 \rightarrow \min$$

where  $C_2^{exp}(t_i)$  - the concentrations found experimentally,  $C_2^{calc}(t_i)$  - their calculated values.

After determining the values  $L_i$  and  $\varepsilon_i$  several options for assigning values  $\varepsilon_1 \neq \varepsilon_2 \neq \varepsilon_3$  for  $\lambda_1, \lambda_2, k_1$  were considered. Taking into account the conjugacy of the roots  $\lambda_1$  and  $\lambda_2$  ( $\lambda_1 > \lambda_2$ ), and sampling two of three  $\varepsilon_1, \varepsilon_2, \varepsilon_3$  possible, we can obtain the following cases:

$$1) \lambda_1 = \varepsilon_1, \lambda_2 = \varepsilon_2, k_1 = \varepsilon_3, \quad (22)$$

$$2) \lambda_1 = \varepsilon_2, \lambda_2 = \varepsilon_3, k_1 = \varepsilon_1, \quad (23)$$

$$3) \lambda_1 = \varepsilon_1, \lambda_2 = \varepsilon_3, k_1 = \varepsilon_2, \quad (24)$$

Further, using equations (12-14) to calculate the coefficients  $A_i$ , we obtain the systems of equations (12<sub>1</sub>-14<sub>1</sub>),

(12<sub>2</sub>-14<sub>2</sub>) and (12<sub>3</sub>-14<sub>3</sub>) for calculating  $L_1^i, L_2^i, L_3^i, i = \overline{1..3}$  respectively:

$$L_1^i = \frac{\varepsilon_3(\varepsilon_1 - k_4) \cdot C_0^1}{(\varepsilon_3 - \varepsilon_1)(\varepsilon_1 - \varepsilon_2)} \quad (12_i)$$

$$L_2^i = \frac{\varepsilon_3(k_4 - \varepsilon_2) \cdot C_0^1}{(\varepsilon_3 - \varepsilon_2)(\varepsilon_1 - \varepsilon_2)} \quad (13_i)$$

$$L_3^i = \frac{\varepsilon_3(\varepsilon_3 - k_4) \cdot C_0^1}{(\varepsilon_3 - \varepsilon_1)(\varepsilon_3 - \varepsilon_2)} \quad (14_i)$$

Since for constants  $L_i$  there are only values  $L_1, L_2, L_3$ , then the above systems of equations can be reduced to the following:

$$L_1^1 = L_2^2 = L_3^3 = L_1 \quad (25_1)$$

$$L_1^2 = L_2^1 = L_3^3 = L_2 \quad (25_2)$$

$$L_1^3 = L_2^2 = L_3^1 = L_3 \quad (25_3)$$

It follows that the initial concentrations for the three variants are related to each other by equality:

$$C_0^1 \varepsilon_3 = C_0^2 \varepsilon_1 = C_0^3 \varepsilon_2 \quad (26)$$

From the equation for calculating the rate constants  $k_4$  (27), it is clear that in the realization of any of the three variants (22-24), its magnitude remains constant:

$$k_4 = -\frac{L_1 \varepsilon_2 \varepsilon_3 + L_2 \varepsilon_1 \varepsilon_3 + L_3 \varepsilon_1 \varepsilon_2}{L_1 \varepsilon_1 + L_2 \varepsilon_2 + L_3 \varepsilon_3} \quad (27)$$

This leads to a very important conclusion in a practical sense:  $k_4$  can serve as the main criterion for the selection of well-founded solutions describing the investigating set of points  $C_2 - t$  for measured solution. To justify this conclusion, let us return to equations (16-17):

For  $k_3 > 0$  we obtain the following inequality:

$$\lambda_1 + \lambda_2 > k_2 + k_4. \quad (28)$$

Then, from the equation (17) we can find  $k_2$ :

$$k_2 = \lambda_1 \lambda_2 / k_4 \quad (29)$$

and substituting it in (28), we obtain a new inequality of the form:

$$k_4^2 - (\lambda_1 + \lambda_2)k_4 + \lambda_1 \lambda_2 < 0. \quad (30)$$

The solution of the last inequality can be represented in this form:

$$k_4 \in (\lambda_2, \lambda_1). \quad (31)$$

This means that the reaction rate constant (2)  $k_3 > 0$  will be positive only if the computed value  $k_4$  will be between the roots  $\lambda_1$  and  $\lambda_2$ .

Otherwise, it will take a negative value. It should be noted that inequality (28) also holds in this case. For the computed values  $\varepsilon_i$ , connected by inequality (20), we find their

maximum -  $\varepsilon_{\max}$  and minimum -  $\varepsilon_{\min}$  meanings. Now, one of the three values  $\varepsilon_i$  ( $\bar{\varepsilon}$ ) belongs to the segment:

$$\bar{\varepsilon} \in (\varepsilon_{\min}, \varepsilon_{\max}).$$

From this it is not difficult to see that for  $k_4$  two variants can be realized:

$$k_4 \in (\varepsilon_{\min}, \bar{\varepsilon}) \text{ and } k_4 \in (\bar{\varepsilon}, \varepsilon_{\max}).$$

Thus, the total number of solutions for equation (18) can be equal to three. Proof of the fact that the dependence  $C_2(t) = f(t)$  can be simultaneously described by three sets of values  $k_i$  and  $C_0$   $S_n$  functions and Laplace transforms were used.

Originally,  $S_n$  denotes definite integrals, called the Laplace transforms:

$$S_n = C_0 \frac{k_1}{k_1 + n} \cdot \frac{n + k_4}{(\lambda_1 + n)(\lambda_2 + n)} \quad (32)$$

Here  $n$  - can be any real number, but for convenience there were taken integer values.

Since in the solution of the inverse problem for equation (11) or (18) it is necessary to determine the values of five unknowns, we can confine ourselves to five equations.

$$x_1 + nx_2 + \frac{1}{n^2} \left( 1 - \frac{S_0}{S_n} \right) x_3 - \frac{S_0}{n \cdot S_n} x_4 = \frac{1}{n} \xi \quad (33)$$

where

$$x_1 = 1 + (\lambda_1 + \lambda_2) / k_1, \quad x_2 = 1 / k_1, \quad x_3 = \lambda_1 \lambda_2, \quad (34)$$

$$x_4 = k_2, \quad \xi = -x_2 x_3 - (x_1 - 1) / x_2.$$

Then, by introducing new notation:

$$\begin{cases} ax_3 + bx_4 = \frac{1}{3} \xi \\ cx_3 + dx_4 = \frac{3}{4} \xi \end{cases} \quad (35)$$

And solving the system of equations (35) and taking into account that  $x_i = B_i \xi$  we define successively all values  $B_i$ :

$$B_4 = \frac{\frac{1}{3}c - \frac{3}{4}a}{dc - ad}, \quad B_3 = \frac{\frac{1}{3}d - \frac{3}{4}b}{ad - bc} \quad (36-37)$$

$$B_2 = -\frac{1}{2} - \left( \frac{S_0}{S_1} - \frac{S_0}{4S_2} - \frac{3}{4} \right) B_3 - \left( \frac{S_0}{S_1} - \frac{S_0}{2S_2} \right) B_4 \quad (38)$$

$$B_1 = 1 - B_2 - \left( 1 - \frac{S_0}{S_1} \right) B_3 + \frac{S_0}{S_1} B_4 \quad (39)$$

Further, substituting  $x_i = B_i \xi$  into equation (34) we obtain the cubic equation (40)

$$B_2^2 B_3 \xi^3 + B_2 \xi^2 + B_1 \xi - 1 = 0, \quad (40)$$

The roots of which are found using the Cardano formula. The nonlinear equation (40) can be solved by a variety of different numerical methods, we chose the simplest of them - Newton's method. The algorithm for finding three values  $\xi_i$  is simple. First, using Newton's method, we determine the value  $\xi_1$ , and then using equality:

$$ax^3 + bx^2 + cx + d = (x - \xi)(ax^2 + (b + a\xi)x + a\xi^2 + b\xi + c) \quad (41)$$

and solving the quadratic equation:

$$ax^2 + (b + a\xi)x + a\xi^2 + b\xi + c = 0 \quad (42)$$

We find the remaining two solutions  $\xi_2$  and  $\xi_3$ .

Thus, it follows from the above proof that for the measured solutions of  $C_2(t)$  and the initial condition  $C_2(0) = 0$ , There are three sets of five permanent  $C_0, k_1, k_2, k_3, k_4$  for the system (3-10).

1. For each of the variants of dependence  $C_2(t) = f(t)$  with specified values of variables  $k_i$  and  $C_0$  there are two more sets of these constants, that is, the inverse problem, in contrast to the straight one has three solutions.

2. Despite the fact that the given (measured) data set  $C_2 - t$  can be described by three sets of constants  $k_i$  and  $C_0$ , only two of them have a physical meaning; The third set with a rate constant  $k_3$ , which has negative value and no physical meaning.

3. Thus, the inverse problem is the determination of the rate constants  $k_i$  and initial concentration  $C_0$  by data  $C_2 - t$  is incorrect, since the number of solutions is not equal to one [4]. And if the data set  $C_2 - t$  is given by a direct problem, then the inverse problem, being ill-posed, has a stable solution. This is confirmed by the fact that one of the solutions found coincides with a given set of rate constants  $k_i$  and  $C_0$ .

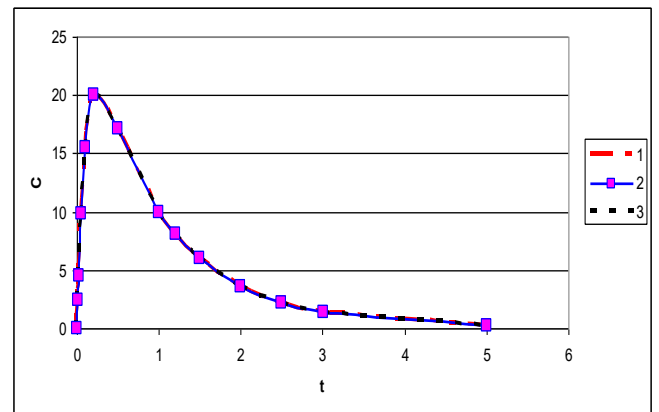


Fig. 2. Dependencies of  $C_2(t)$  on time for different values  $\xi_{1,2,3}$ .

This fact also serves as a criterion for the correctness of the proposed mathematical apparatus and the calculations performed. In addition, the results of the study completely confirm the reliability of the data obtained earlier, where the proof of the non-uniqueness of the solution for the inverse problem was obtained in a different way [1, 2].

During the solution of inverse problem from experimental data,  $C_2 - t$  is complicated by the fact that the instability is added to the problem of nonuniqueness of the solution. The problem of incorrectness of the inverse problem, caused by the instability of its solution, is one of the main problems in this field of knowledge. Its severity can be reduced by the continuous improvement of the optimization procedures used and the quality of the experiment. However, completely this problem can not be solved in principle.

IV. RESULTS AND DISCUSSION

To clarify the stability of finding the coefficients of the model of pharmacokinetics, experimental values of the dependence  $C_2(t) = A_1e^{-\lambda_1 t} + A_2e^{-\lambda_2 t} - A_3e^{-k_1 t}$  on time for values  $C_0 = 50, k_1 = 10, k_2 = 1, k_3 = 5, k_4 = 3$ . with a minimum absolute error in 1%.

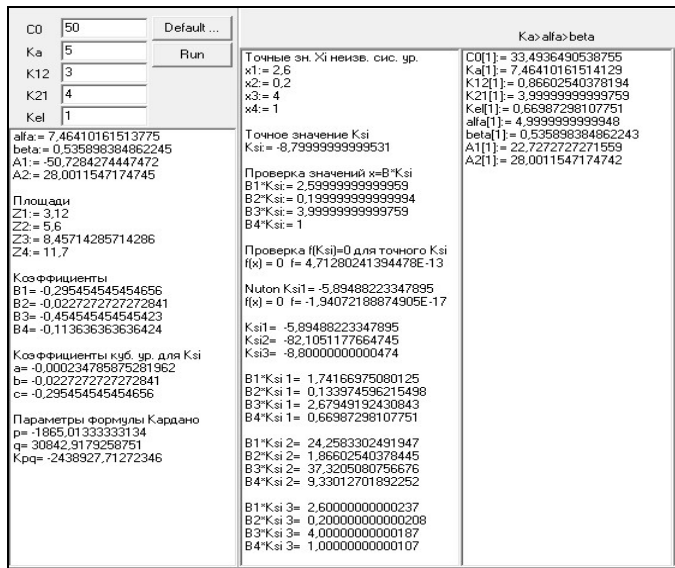


Fig. 3. Results of a numerical experiment, confirming the existence of three solutions for the equations (18) and respectively (11).

Using the proven methods of solving inverse problems, unknown parameters for the given experimental data were found. Unfortunately, the found parameters are very different from the model parameters. We can make sure to see the following figure.

The screenshot shows a table with columns for 'Точки в эксперименте', 'Полученные данные', 'График', 'Найденные данные 1', 'График для отобранных', 'График сравнения методов', and 'Данные'. The table lists parameters like A1, A2, afa, beta, Ka, AUMC, CL, MRT, Vss, K12, K21, K10, Vbeta, C0, V1, and SD for different methods such as 'Линейный регр.', 'Нелинейные регр.', 'МДХ(Л)', 'МДХ(Н)', and 'МСМ'.

Fig. 4. Unknown parameters for the given experimental data with a minimum absolute error of 1%. were found .

You can also illustrate the graphical data for the parameters found using numerical methods.

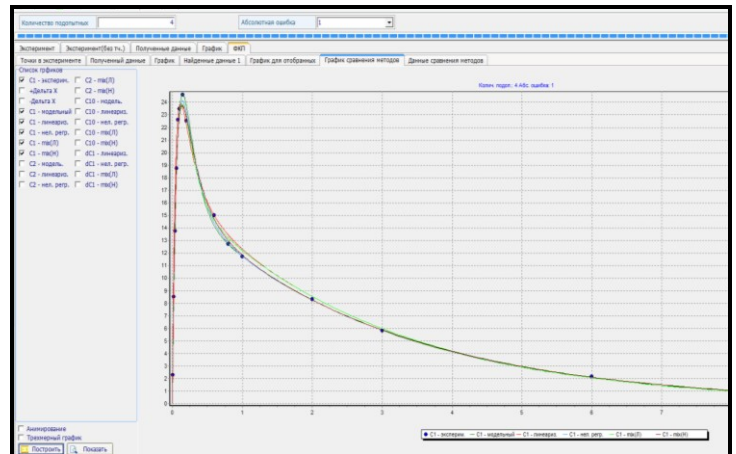


Fig. 5. Graphical dependences of concentration in the central chamber for the data from Fig. 4.

Here we can see a good coincidence for the central chamber of a linear two-chamber pharmacokinetics model with absorption. For the second chamber, the concentration curves are very different from the actual model concentration curve. This can be seen in the Fig. 6.

It can be seen from the figure that the concentration curves of the preparation in the peripheral chamber by quantitative values are almost two times different from the model preset values (red curve).

In the literature, there are many examples of the analysis of pharmacokinetic data [5-8]. A model is constructed for a particular process. Equations describing the corresponding model are given. There used the least squares method (LSM) for determining the parameters involved in the model equations, but often poorly or do not pay attention to the estimated statistical value.

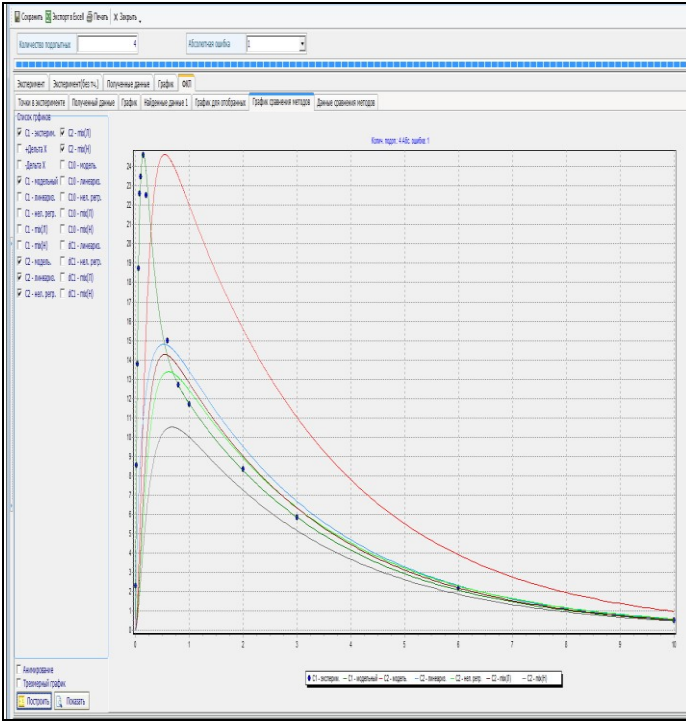


Fig. 6. Graphical dependencies of concentration in the peripheral chamber.

The purpose of this paper presents several important statistical aspects included in the describing equations and finding the values of the pharmacokinetic parameters with the corresponding confidence intervals. The general principle and procedure of the method is proposed in order to obtain statistical parameters.

A two-compartment model of pharmacokinetics with intravascular injection is considered. The change in the concentration of drugs in the blood is described by the equation (54):

$$C(t_i) = A_1 e^{-\alpha t_i} + A_2 e^{-\beta t_i} - (A_1 + A_2) e^{-k_A t_i} \quad (43)$$

It is well known that the best statistical parameters can be determined using LSM. The present paper deals with the case of drug distribution, which are described by four parameters. When the experimentally found values  $C_i^{\text{exp}}$  characterizes by equation  $C(t_i, A_1, A_2, \alpha, \beta, k_A)$ , parameter

$A_1, A_2, \alpha, \beta, k_A$  should give the minimum value of the weighted sum of squared differences between  $C_i^{\text{exp}}$  and  $C(t_i, A_1, A_2, \alpha, \beta, k_A)$ , that is,

$$S = \sum_{i=1}^N (C_i^{\text{exp}} - C(t_i, A_1, A_2, \alpha, \beta))^2 \cdot \omega_i \rightarrow \min \quad (44)$$

In our case  $\omega_i = 1$ ,  $N$  is the number of experimental points. At  $S \rightarrow \min$  determines the values  $A_1, A_2, \alpha, \beta, k_A$  in equation (54).

When  $A_1^o, A_2^o, \alpha^o, \beta^o, k_A^o$  is the solution of inverse problem (54) for given experimental data  $C_i^{\text{exp}}$ , then

$A_1^o, A_2^o, \alpha^o, \beta^o, k_A^o$  accepted as approximate values  $A_1, A_2, \alpha, \beta, k_A$  and respectively, the best parameters can be given in the following form

$$A_1 = A_1^o + \Delta A_1, A_2 = A_2^o + \Delta A_2, \alpha = \alpha^o + \Delta \alpha, \beta = \beta^o + \Delta \beta, k_A = k_A^o + \Delta k_A$$

where  $\Delta A_1, \Delta A_2, \Delta \alpha, \Delta \beta, \Delta k_A$  are growth for parameters  $A_1, A_2, \alpha, \beta, k_A$ , respectively.

The dependence  $C(t_i, A_1, A_2, \alpha, \beta, k_A)$  is expanded in a Taylor series for  $A_1^o, A_2^o, \alpha^o, \beta^o, k_A^o$ . Then we determine that

$$\Delta C_i = C_i^{\text{exp}} - C(t_i, A_1, A_2, \alpha, \beta, k_A)$$

Further, using the Taylor series expansion, we obtain the following equations:

$$\Delta C_i = \delta_0^i - \delta_{A_1}^i \Delta A_1 - \delta_{A_2}^i \Delta A_2 - \delta_{\alpha}^i \Delta \alpha - \delta_{\beta}^i \Delta \beta - \delta_{k_A}^i \Delta k_A$$

where

$$\delta_0^i = C_i^{\text{exp}} - C(t_i, A_1^o, A_2^o, \alpha^o, \beta^o),$$

$$\delta_{A_1}^i = \frac{\partial C(t_i, A_1^o, A_2^o, \alpha^o, \beta^o)}{\partial A_1},$$

$$\delta_{A_2}^i = \frac{\partial C(t_i, A_1^o, A_2^o, \alpha^o, \beta^o)}{\partial A_2},$$

$$\delta_{\alpha}^i = \frac{\partial C(t_i, A_1^o, A_2^o, \alpha^o, \beta^o)}{\partial \alpha},$$

$$\delta_{\beta}^i = \frac{\partial C(t_i, A_1^o, A_2^o, \alpha^o, \beta^o)}{\partial \beta}.$$

Based on the LSM principle, the following system of equations is given for unknown quantities  $\Delta A_1, \Delta A_2, \Delta \alpha, \Delta \beta, \Delta k_A$ .

$$\begin{cases} (\delta_{A_1}, \delta_{A_1}) \Delta A_1 + (\delta_{A_2}, \delta_{A_2}) \Delta A_2 + (\delta_{\alpha}, \delta_{\alpha}) \Delta \alpha + (\delta_{\beta}, \delta_{\beta}) \Delta \beta + (\delta_{k_A}, \delta_{k_A}) \Delta k_A = (\delta_{A_1}, \delta_0) \\ (\delta_{A_1}, \delta_{A_2}) \Delta A_1 + (\delta_{A_2}, \delta_{A_2}) \Delta A_2 + (\delta_{\alpha}, \delta_{A_2}) \Delta \alpha + (\delta_{\beta}, \delta_{A_2}) \Delta \beta + (\delta_{k_A}, \delta_{A_2}) \Delta k_A = (\delta_{A_2}, \delta_0) \\ (\delta_{A_1}, \delta_{\alpha}) \Delta A_1 + (\delta_{A_2}, \delta_{\alpha}) \Delta A_2 + (\delta_{\alpha}, \delta_{\alpha}) \Delta \alpha + (\delta_{\beta}, \delta_{\alpha}) \Delta \beta + (\delta_{k_A}, \delta_{\alpha}) \Delta k_A = (\delta_{\alpha}, \delta_0) \\ (\delta_{A_1}, \delta_{\beta}) \Delta A_1 + (\delta_{A_2}, \delta_{\beta}) \Delta A_2 + (\delta_{\alpha}, \delta_{\beta}) \Delta \alpha + (\delta_{\beta}, \delta_{\beta}) \Delta \beta + (\delta_{k_A}, \delta_{\beta}) \Delta k_A = (\delta_{\beta}, \delta_0) \\ (\delta_{A_1}, \delta_{k_A}) \Delta A_1 + (\delta_{A_2}, \delta_{k_A}) \Delta A_2 + (\delta_{\alpha}, \delta_{k_A}) \Delta \alpha + (\delta_{\beta}, \delta_{k_A}) \Delta \beta + (\delta_{k_A}, \delta_{k_A}) \Delta k_A = (\delta_{k_A}, \delta_0) \end{cases} \quad (45)$$

where

$$\delta_{A_1} = \{\delta_{A_1}^1, \delta_{A_1}^2, \dots, \delta_{A_1}^N\}, \delta_{A_2} = \{\delta_{A_2}^1, \delta_{A_2}^2, \dots, \delta_{A_2}^N\}, \delta_{\alpha} = \{\delta_{\alpha}^1, \delta_{\alpha}^2, \dots, \delta_{\alpha}^N\},$$

$$\delta_{\beta} = \{\delta_{\beta}^1, \delta_{\beta}^2, \dots, \delta_{\beta}^N\}, \delta_{k_A} = \{\delta_{k_A}^1, \delta_{k_A}^2, \dots, \delta_{k_A}^N\}$$

$$\delta_{A_1}^i = e^{-\alpha^o t_i} - e^{-k_A^o t_i}, \delta_{A_2}^i = e^{-\beta^o t_i} - e^{-k_A^o t_i}, \delta_{\alpha}^i = -A_1^o t_i e^{-\alpha^o t_i}, \delta_{\beta}^i = -A_2^o t_i e^{-\beta^o t_i},$$

$$\delta_{k_A}^i = (A_1^o + A_2^o) t_i e^{-k_A^o t_i}.$$

The best parameters can be obtained by the roots of the above system (56). Solving the system of equations by the numerical

method of Gauss determine the values of the unknowns  $\Delta A_1, \Delta A_2, \Delta \alpha, \Delta \beta, \Delta k_A$

The system (56) can be written in the following matrix form

$$\Lambda \cdot \Delta_x = \Delta_0$$

We denote by  $C$  the inverse matrix in (45)

$$C = \Lambda^{-1}$$

The solution  $\Delta A_1, \Delta A_2, \Delta \alpha, \Delta \beta, \Delta k_A$  of system (45) can be represented in vector form:

$$\Delta_x = \Lambda^{-1} \cdot \Delta_0$$

here

$$\Lambda = \begin{pmatrix} (\delta_{A_1}, \delta_{A_1}) & (\delta_{A_1}, \delta_{A_2}) & \dots & (\delta_{A_1}, \delta_{k_A}) \\ (\delta_{A_1}, \delta_{A_2}) & (\delta_{A_2}, \delta_{A_2}) & \dots & (\delta_{A_2}, \delta_{k_A}) \\ \dots & \dots & \dots & \dots \\ (\delta_{A_1}, \delta_{k_A}) & (\delta_{A_2}, \delta_{k_A}) & \dots & (\delta_{k_A}, \delta_{k_A}) \end{pmatrix}$$

$$\Delta_0 = ((\delta_{A_1}, \delta_o), (\delta_{A_2}, \delta_o), (\delta_\alpha, \delta_o), (\delta_\beta, \delta_o), (\delta_{k_A}, \delta_o))$$

$$\Delta_x = (\Delta A_1 \ \Delta A_2 \ \Delta \alpha \ \Delta \beta \ \Delta k_A)^T$$

The statistical values are given by the following equations.

$$S = (\delta_o, \delta_o) - (\delta_{A_1}, \delta_o) \Delta A_1 - (\delta_{A_2}, \delta_o) \Delta A_2 - (\delta_\alpha, \delta_o) \Delta \alpha - (\delta_\beta, \delta_o) \Delta \beta - (\delta_{k_A}, \delta_o) \Delta k_A$$

$$\sigma^2 = S / (N - 2) - \text{sum of squares.}$$

The standard deviation of the parameters of equation (43)

$A_1, A_2, \alpha, \beta, k_A$ :

$$SD_{A_1} = \sqrt{c_{11} \sigma^2}, SD_\alpha = \sqrt{c_{33} \sigma^2}, SD_\beta = \sqrt{c_{44} \sigma^2},$$

$$SD_{k_A} = \sqrt{c_{55} \sigma^2}.$$

where  $c_{ii}$  – elements of the inverse matrix of system of equations (56).

The covariance coefficient can be expressed as the percentage

$$\text{of the coefficient of change } \%CV = \frac{SD}{\theta_i} \times 100$$

Where  $\theta_i$  is one of the parameters  $A_1, A_2, \alpha, \beta, k_A$ .

Confidence intervals at 95% for each parameter can be given by the following equation:

$$CI = SD \times t_{95}.$$

By knowing the values  $SD_{A_1}, SD_{A_2}, SD_\alpha, SD_\beta, SD_{k_A}$  it needs to be determined  $SD_{C_0}, SD_{k_{21}}, SD_{k_{12}}, SD_{k_{10}}$

Let's write the formulas for constants:

$$k_{21} = \frac{\alpha\beta(A_1 + A_2) - A_1 k_A \beta - A_2 k_A \alpha}{A_1 \alpha + A_2 \beta - (A_1 + A_2) k_A};$$

$$k_{10} = \frac{\alpha\beta}{k_{21}};$$

$$k_{12} = (\alpha + \beta) - k_{21} - k_{10};$$

$$C_0 = \frac{A_2(\alpha - \beta)(k_A - \beta)}{k_A(k_{21} - \beta)};$$

1.  $SD_{k_{21}} = k_{21} \sqrt{\left(3 \left(\frac{SD_{k_A}^2}{k_A^2} + \frac{SD_\alpha^2}{\alpha^2} + \frac{SD_\beta^2}{\beta^2}\right) + 4 \left(\frac{SD_{A_1}^2}{A_1^2} + \frac{SD_{A_2}^2}{A_2^2}\right)\right)}$
2.  $SD_{k_{10}} = k_{10} \sqrt{\left(\frac{SD_{k_{21}}^2}{k_{21}^2} + \frac{SD_\alpha^2}{\alpha^2} + \frac{SD_\beta^2}{\beta^2}\right)}$
3.  $SD_{k_{12}} = \sqrt{SD_\alpha^2 + SD_\beta^2 + SD_{k_{21}}^2 + SD_{k_{10}}^2}$
4.  $SD_{C_0} = C_0 \sqrt{4 \left(\frac{SD_{A_2}^2}{A_2^2} + \frac{SD_\beta^2}{\beta^2}\right) + 2 \frac{SD_\alpha^2}{\alpha^2} + 5 \frac{SD_{k_A}^2}{k_A^2} + \frac{SD_{k_{21}}^2}{k_{21}^2}}$

Метод	Параметр	Значение	CV	CI
Линейная регрессия	A1	16.46854932519	3.050231	18.52155
	A2	17.34228267292	2.438618	14.06169
	alpha	4.718390538666	1.35358	28.68733
	beta	0.354191497760	0.08609233	24.30697
	kA	23.26501100471	3.640919	15.64976
Нелинейная регрессия	A1	31.23899593983	1.133671	3.629027
	A2	16.31612538114	0.8724051	5.346889
	alpha	5.355364891643	0.4384618	7.892583
	beta	0.167497761438	0.03335458	9.805339
	kA	15.0552397424	0.7843642	5.20981
Метод Мх(П)	A1	37.35213053454	1.174233	3.143685
	A2	17.34228267292	0.8797977	5.073137
	alpha	6.834952828854	0.5594177	8.184661
	beta	0.354191497760	0.03463304	9.778056
	kA	14.694034999086	0.848204	5.772438
Метод Мх(Н)	A1	22.28174304814	2.289667	10.27598
	A2	16.31612538114	1.845457	11.31063
	alpha	4.604078048098	0.8457372	18.36931
	beta	0.340167497761	0.065492	19.25287
	kA	17.11479149564	1.781992	10.412

Fig. 7. Statistical data for the found pharmacokinetic parameters by several numerical methods.

An analytic proof of the existence of three solutions in the solution of the inverse problem for equation (11) and the representation of the algorithm for their finding are given in this paper. The theoretical proof of the nonuniqueness of the solution is confirmed by numerical calculations [9-16].

In the numerical solution of (51) one can find one solution for equation (11). The remaining two solutions can be determined with the help of the solution found.

## V. CONCLUSION

After numerous numerical experiments in solving the inverse problem for equation (11), finding some constants through linearization is quite effective in terms of iterative



algorithms and in the accuracy of determining the parameters. Consider the case when  $\lambda_2 < \lambda_1 < k_1$ . Next, there given an algorithm for finding the constants of equation (11):

1. Through linearization we find the values  $\lambda_2, A_2$ .

2. Knowing the maximum value and using equality  $C_2'(t_{\max}) = 0$  consider  $A_1$  in form  $A_1 = (k_1 A_2 e_{k_1} - \lambda_2 A_2 e_{\lambda_2}) / (\lambda_1 e_{\lambda_1} - k_1 e_{k_1})$ , where  $e_i = e^{-it_{\max}}$ .

3. After some simple transformations, we have the following equation depending on two variables  $k_1, \lambda_1$ :

$$C(t) = \frac{A_2(k_1 - \lambda_2 e^{(k_1 - \lambda_2)t})}{\lambda_1 e^{(k_1 - \lambda_1)t} - k_1}$$

For the numerical implementation of the above algorithm, there is no complication. Condition  $\lambda_1 < k_1$  reduces the plane of research twice. To solve the third point, we can use numerical methods for solving a system of two nonlinear equations.

When solving the inverse problem from experimental data  $C_2 - t$  is complicated by the fact that the instability is added to the problem of nonuniqueness of the solution. The problem of incorrectness of the inverse problem, caused by the instability of its solution, is one of the main problems in this field of knowledge. Its severity can be reduced by the continuous improvement of the optimization procedures used and the quality of the experiment. However, completely this problem can not be solved in principle.

In Fig. 7 that the standard deviation is quite satisfactory. Also, it can be seen from Fig. 6 that the concentration curves of the preparation in the peripheral chamber are almost twice as large as the model preset (red curve) by quantitative values. This suggests that we are still far from finding the pharmacokinetic parameters correctly.

As the numerical results show, when exponential functions are used, there can be found a set of pharmacokinetic parameters that very well characterize the given experimental data. It can be seen that the concentration curves of the central chamber describe the data of exact solution taken with an error of 1%, but there is no similarity in the peripheral chamber with model pharmacokinetic parameters. They differ from each other several times. This can definitely indicate that even for simple linear models of pharmacokinetics, there is no single correct algorithm for determining or finding the pharmacokinetic parameters.

#### REFERENCES

[1] B.A. Urmashhev, Zh.R. Ualiev, N.A. Asmanova, On some problems of solving inverse problems of the chemical kinetics of reactions with the formation of intermediate compounds. // 2) Consecutive reactions  $a \rightarrow b \rightarrow c$  with reversible interaction  $b \leftrightarrow d$  // Materials of the 4th international symposium "Combustion and Plasma Chemistry". 12-14 September 2007. P. 278-280.

[2] B.A. Urmashhev, Zh.R. Ualiev, N.A. Asmanova, On some problems of solving inverse problems of the chemical kinetics of reactions with the formation of intermediate compounds. // 3) Conditions for the coincidence of the curves  $c = f(t)$  of the component in the systems  $a \rightarrow b \rightarrow c$  (i) and  $a \rightarrow b \rightarrow c, b \leftrightarrow d$  (ii) // Materials of the 4th international symposium «Combustion and Plasma Chemistry». 12-14 September 2007. P. 281-284.

[3] S.D. Varfolomeev, K.G. Gurevich, Biokinetics. Faire-Press, -M: 1999, -720s.

[4] M. P. Adam, Foundations in Pharmacokinetics // Copyright 2013, p.175.

[5] V.I. Yunkerov, S.G. Grigoriev, Mathematico-statistical processing of medical research data. - Spb.: VMEDA, 2002.-266 p.

[6] O.Yu. Rebrova, Statistical analysis of medical data. Application of a package of applied programs STATISTICA.-M.: MediaSfera, 2002.- 212 p.

[7] W.L. Chiou, Critical Evaluation of the Potential Error in Pharmacokinetic Studies of Using the Linear Trapezoidal Rule Method for the Calculation of the Area Under the Plasma Level-Time Curve. // J. Pharmacokin. Biopharm., 1978, 6, №. 6. -P. 539-546.

[8] I. Gaidyshev, Analysis and data processing: special reference book - St. Petersburg, Peter, 2001.-752 p.

[9] S. Leon, Yu. Andrew, Applied Biopharmaceutics and pharmacokinetics // p. 47-62, 4-th edition.

[10] L. B. Peter, R.D. Danny, Pharmacokinetics in Drug Development: Advances and Applications, volume 3. Springer, 2011, p. 78

[11] D. Z. D'Argenio, A. Schumitzky, X. Wang, Adapt 5 user's guide: Pharmacokinetic/pharmacodynamic systems analysis software. Biomedical Simulations Resource, Los Angeles, 2009.

[12] V.I. Sergienko, R. Gelliff, I.B. Bondareva, Applied pharmacokinetics: main provisions and clinical application. -M.: RAMS, 2003. -208 p.

[13] S. A. Hill, Pharmacokinetics of drug infusions. Continuing Education in Anaesthesia, Critical Care & Pain, 4(3):76-80, 2004.

[14] K.C. Yeah, K.C. Kwan, A Comparison of Numerical Integrating Algorithms by Trapezoidal, Lagrange, and Spline Approximation.// J. Pharmacokin. Biopharm., 1978, 6, №.1, - P.79-98.

[15] S.I. Kabanikhin, D.A. Voronov, O.I. Krivorotko, A.A. Grozd, Identifikatsiyemost dinamicheskoi sistem na primere modelei farmakokinetiki i immynologii // Sibirskie elektronnye matematicheskie izvestiia, Tom 12, dekabr, Novosibirsk 2015 g. - S.182-188.

[16] S.I. Kabanikhin, O.I. Krivorotko, Identification of biological models described by systems of nonlinear differential equations // Journal of Inverse and Ill-Posed Problems, Vol. 23, Iss. 5, 2015. - P. 519-527. DOI: 10.1515/jiip-2015-0072.