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# On estimates of solutions of the linear stationary problem of magnetohydrodynamics problem in Sobolev spaces

Khonatbek Khompysh and Sharypkhan Sakhaevich Sakhaev

*Al-Farabi Kazakh National University, 050038, Almaty, Kazakhstan*

**Abstract.** In this paper, we get estimates in Sobolev spaces for solutions of stationary linear problem arising in magnetohydrodynamics. The problem is studied in the multiply connected domains.

**Keywords:** Magnetohydrodynamics,  $L_p$ -estimate, Sobolev spaces, Multi-connected domains.

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## STATEMENT OF THE PROBLEM

Let  $\Omega_1$ , bounded domain in  $\mathbb{R}^3$  with a smooth boundary  $S_1$ , be strictly interior subdomain  $\Omega$  from abroad  $S$  and let  $\Omega_2 = \Omega \setminus \Omega_1$ . In this paper, we consider the linear problem that is the system of Maxwell's equations with excluded bias current

$$\begin{aligned} \operatorname{rot} \vec{H}(x) - \sigma \vec{E}(x) &= \vec{j}(x), \\ \operatorname{div} \vec{H}(x) &= 0, \\ \operatorname{rot} \vec{E}(x) &= 0 \end{aligned} \quad (1)$$

at a given  $\vec{j}(x)$ ,  $x \in \Omega_1$ . Thus,  $\operatorname{rot} \vec{H} = 0$ ,  $\operatorname{div} \vec{H} = 0$ ,  $x \in \Omega_2$  and fair

$$\begin{aligned} [H_n] &= 0, [\vec{H}_\tau] = 0, x \in S_1 \\ H_n &= 0, x \in S. \end{aligned} \quad (2)$$

Under  $[u]$  jump of the function  $u(x)$ ,  $x \in \Omega_1 \cup \Omega_2$  on the surface  $S_1$ :  $[u] = u^1(x) - u^2(x)$ ,  $u^{(i)} = u(x)|_{x \in \Omega_i}$ ,  $H_n = \vec{H} \cdot \vec{n}$  and  $\vec{H}_\tau = \vec{H} - \vec{n} H_n$  are normal and tangential components of the vector  $\vec{H}(x)$  on  $S$  and  $S_1$ ,  $\mu$  is a piecewise constant function, equal  $\mu_i$  in  $\Omega_i$ ,  $i = 1, 2$ ,  $\mu_i > 0$ .

Problem (1)-(2) arises in the study of problems of magneto hydrodynamics, [1–3] in which  $\Omega_1$  is an area, filled with a viscous incompressible electrically conducting fluid,  $\Omega_2$  is a vacuum surrounding,  $S$  is a perfectly conducting surface,  $\vec{H}(x)$  is the magnetic field strength. Relations (1) represent a linearized stationary equations of Maxwell (with exceptional bias currents) and (2) represent the standard conditions at the boundary of the magnetic field. We assume the field  $\Omega_1$  and  $\Omega_2$  simply connected. Then equations  $\operatorname{rot} \vec{H} = 0$ ,  $\operatorname{div} \vec{H} = 0$  in  $\Omega_2$  entails  $\vec{H}^2(x) = \nabla \varphi(x)$ , where  $\varphi(x)$  is a solution of the following Neumann problem

$$\begin{aligned} \nabla^2 \varphi(x) &= 0, x \in \Omega_2, \frac{\partial \varphi}{\partial n} \Big|_{x \in S} = 0, \\ \mu_2 \frac{\partial \varphi}{\partial n} \Big|_{x \in S_1} &= \mu_1 \vec{H}^{(1)} \cdot \vec{n} \Big|_{x \in S_1}, \end{aligned} \quad (3)$$

and problem (1)-(2) can be written as

$$\begin{aligned}
\frac{1}{\sigma} \operatorname{rot} \operatorname{rot} \vec{H}^{(1)}(x) &= \vec{g}(x), \quad \operatorname{div} \vec{H}^{(1)}(x) = 0, \\
\vec{H}^{(2)}(x) &= \nabla \varphi(x), \\
\nabla^2 \varphi(x) &= 0, \quad x \in \Omega_2, \quad \left. \frac{\partial \varphi}{\partial n} \right|_{x \in S} = 0, \\
\mu_2 \left. \frac{\partial \varphi}{\partial n} - \mu_1 \vec{H}^{(1)} \cdot \vec{n} \right|_{x \in S_1} &= 0, \\
\vec{H}_\tau^{(1)} &= \nabla_\tau \varphi(x), \quad x \in S_1,
\end{aligned} \tag{4}$$

where  $\vec{g}(x) = \frac{1}{\sigma} \operatorname{rot} \vec{j}(x)$ .

Hence,  $\vec{H}^2(x)$  is completely determined by  $\vec{H}^1 \cdot \vec{n} \Big|_{x \in S_1}$ . Conditions on the surface  $S_1$  for the vector  $\vec{H}$  can be briefly written as  $\vec{H}_\tau(x) = B(\vec{H} \cdot \vec{n})$ , where  $B$ —nonlocal linear operator. We use annotation of functional spaces and norms accepting in [4, 5].

**Theorem 1.** *Suppose that  $\vec{g}(x) \in L_p(\Omega_1)$  and the conditions*

$$\begin{aligned}
\nabla \cdot \vec{g} &= 0, \quad \nabla \cdot \vec{H}(x) = 0, \quad x \in \Omega_1, \\
\vec{H}_\tau^{(1)} &= B(\vec{H}^{(1)} \cdot \vec{n})
\end{aligned} \tag{5}$$

hold. Then, problem (1)-(2) has a unique solution  $\vec{H}^{(1)} \in W_p^2(\Omega_1)$  and it satisfies

$$\|\vec{H}^{(1)}\|_{W_p^2(\Omega_1)} \leq c \|\vec{g}\|_{L_p(\Omega_1)}. \tag{6}$$

Recall that  $W_p^r(\Omega_1)$ ,  $r = [r] + \lambda$ ,  $0 < \lambda < 1$  is the space with the norm

$$\|v\|_{W_p^r(\Omega_1)} \leq \left( \sum_{0 \leq j \leq [r]} \|D^j v\|_{L_p(\Omega_1)}^p + \sum_{|j|=[r]} \int_{\Omega_1} \int_{\Omega_1} |D^j v(x) - D^j v(y)|^p \frac{dx dy}{|x-y|^{3+p\lambda}} \right)^{1/p}.$$

It is easy to check that (6) implies the same estimate for  $\vec{H}^2(x)$ . Indeed, the solution of problem (3) satisfies

$$\|\nabla \varphi\|_{W_p^2(\Omega_2)} \leq c \|\vec{H}^{(1)} \cdot \vec{n}\|_{W_p^{1-1/p}(S_1)} \leq c \|\vec{H}^{(1)}\|_{W_p^2(\Omega_1)}. \tag{7}$$

Furthermore, since

$$\mu_2 \int_{\Omega_2} \nabla \varphi \nabla \eta dx = - \int_S \mu_1 \vec{H}^{(1)} \cdot \vec{n} \eta ds = - \mu_1 \int_{\Omega_1} \vec{H}^{(1)} \cdot \vec{n} \eta ds = - \mu_1 \int_{\Omega_1} \vec{H}^{(1)} \nabla \eta dx$$

for any  $\eta \in W_p^1(\Omega)$ , we obtain

$$\|\nabla \varphi\|_{L_p(\Omega_2)} \leq c \|\vec{H}^{(1)}\|_{L_p(\Omega_1)}. \tag{8}$$

From (8)

$$\|\vec{H}^{(2)}\|_{W_p^2(\Omega_2)} \leq c \|\vec{H}^{(1)}\|_{W_p^2(\Omega_1)}. \tag{9}$$

We also have  $\vec{H}^2 = \nabla \varphi$ , where  $\varphi(x)$  is the weak solution of the Neumann problem

$$\begin{aligned}
\nabla^2 \varphi &= 0, \quad x \in \Omega_2, \\
\left. \frac{\partial \varphi}{\partial n} \right|_S &= 0, \quad \mu_2 \left. \frac{\partial \varphi}{\partial n} - \mu_1 \vec{H}^{(1)} \cdot \vec{n} \right|_{S_1} = 0,
\end{aligned} \tag{10}$$

i.e., the function  $\varphi(x)$  satisfies the following integral identity, for all test function  $\eta \in J_2^1(\Omega_1) \cap J_2^1(\Omega_2)$ , satisfying boundary conditions (10)

$$\mu_2 \int_{\Omega_2} \nabla \varphi \nabla \eta dx + \int_{\Omega_1} \mu_1 H^{(1)} \cdot \nabla \eta dx = 0. \quad (11)$$

Solenoidal condition (for example  $\nabla \vec{g} = 0$ ) understood in the usual meaning as  $\int_{\Omega_1} \vec{g} \cdot \nabla \eta dx = 0$  for any smooth  $\eta$  vanishing on  $S_1$ .

Condition (5) means for  $p > 3/2$  as equality trace function  $\vec{H}^1(x)$  and on  $S$ :  $\vec{H}_\tau^1 = \nabla_\tau \varphi = \vec{H}_\tau^2 \in W_p^{2-3/p}(S_1)$ . At  $p < 3/2$  it makes no sense, and if  $p = 3/2$  understood as an integral limitations

$$\int_{\Omega_2} \left( \vec{k} - \vec{H}^{(2)} - \vec{n} \cdot \vec{n}^* \left( \vec{k} - \vec{H}^{(2)} \right) \rho^{-1}(x) \right) dx,$$

where  $\rho(x)$  is a smooth function, equal  $dist(x, S_1)$  around  $S_1$ ,  $\vec{n}^*$  is a smooth extension of the normal  $\vec{n}$  inside  $\Omega_2$ ,  $\vec{k} \in W_{3/2}^{2/3}(\Omega_2)$  is continuation of the vector field  $\vec{H}^1 \in W_{3/2}^{2/3}(\Omega_1)$  with preservation of class.

**Remark 1.** For applications to the magneto hydrodynamics most interesting case  $p > 3/2$ .

## PROBLEM (1)-(2) IN MULTIPLY CONNECTED DOMAINS $\Omega_1$ AND $\Omega$

We turn to a discussion of problem (1)-(2). In the case of many areas of connectedness convenient consider it in the form

$$\begin{aligned} rot \vec{E} &= 0, \quad div \vec{H}(x) = 0, \quad x \in \Omega_1 \cup \Omega_2, \\ rot \vec{H} &= \sigma \vec{E} + \vec{j}(x), \quad x \in \Omega_1, \\ rot \vec{H}(x) &= 0, \quad div \vec{E} = 0, \quad x \in \Omega_2, \\ [\mu \vec{H} \cdot \vec{n}] &= 0, \quad [\vec{H}_\tau] = 0, \quad [\vec{E}_\tau] = 0, \quad x \in S_1, \\ \vec{H} \cdot \vec{n} &= 0, \quad \vec{E}_\tau = 0, \quad x \in S, \end{aligned} \quad (12)$$

where  $\vec{j}(x)$  is given and  $\vec{E}$  is additional unknown vector field.

It is clear that,  $\vec{E}$  easily eliminated from (12) by (1)-(2) with  $\vec{g}(x) = \sigma^{-1} rot \vec{j}$ . Thus,  $\vec{H}^1(x)$  satisfies

$$\sigma^{-1} rot rot \vec{H}^{(1)} = \sigma^{-1} rot \vec{j}(x), \quad div \vec{H}^{(1)} = 0, \quad x \in \Omega_1, \quad (13)$$

$$\mu_1 \vec{H}^{(1)} \vec{n} = \mu_2 \frac{\partial \varphi}{\partial n}, \quad \vec{H}_\tau^{(1)} = \nabla_\tau \varphi + \vec{u}_\tau(x), \quad x \in S_1, \quad \vec{H}^{(1)}(x) = 0, \quad (14)$$

where function  $\varphi$ , as above, a solution of (3). In addition, it is easy to check that  $\vec{H}(x)$  satisfies the integral identity

$$\int_{\Omega_1} rot \vec{H} \cdot rot \psi dx = \int_{\Omega_1} \vec{j}(x) rot \vec{\psi}(x) dx, \quad (15)$$

where  $\vec{\psi}$  is any vector field of the  $rot \vec{\psi} \in W_2^1(\Omega_1) \cap W_2^1(\Omega_2)$ ,  $rot \vec{\psi} = 0$  in  $\Omega_2$  and continuous tangential component on  $S_1$ . Let  $\vec{u}_m^*$  be solenoidal smooth extension  $\vec{u}_m$  in the area  $\Omega_1$ . In (15) putting  $\vec{\psi} = \vec{u}_m^*$ , we get

$$- \int_{\Omega_1} rot rot \vec{H}^{(1)} \cdot \vec{u}_m^* dx + \int_{\Omega_1} rot \vec{j}(x) \cdot \vec{u}_m^* dx = \int_{S_1} (rot \vec{H}^{(1)} - \vec{j})(\vec{n} \times \vec{u}_m) dS,$$

that by (13) and  $\vec{H}^2 = \nabla \varphi + \vec{u}(x)$ ,  $\vec{u}(x) = \sum_{j=1}^{h+h_1} K_j \cdot \vec{u}_j(x)$  is reduced to

$$\mu_2 \sum_{j=1}^{h+h_1} C_{mj} k'_j = - \int_{S_1} \left( \sigma^{-1} \text{rot} \vec{H}^{(1)} - \sigma^{-1} \vec{j} \right) (\vec{n} \times \vec{u}_m) dS, \quad (16)$$

where  $h$  and  $h_1$  are the first Betti numbers of  $\Omega$  and  $\Omega_1$ .

We show that  $\vec{H}$  is reduced to the evaluation  $\vec{H}^1(x)$ , satisfying (16) and

$$\sum_{j=1}^{h+h_1} k_j C_{mj} = \int_{\Omega_2} \vec{H}^2(x) \cdot \vec{u}_m(x) dx,$$

where  $C_{mj} = \int_{\Omega_2} u_m(x) \vec{u}_j(x) dx$  are elements of a positive definite matrix.

Problem (13), (14) differs from (4) only in the presence of heterogeneity in the boundary condition. In the same way as above, we can prove

$$\begin{aligned} \|\vec{H}^{(1)}\|_{W_p^2(\Omega)} &\leq c \left[ \|\text{rot} \vec{j}(x)\|_{L_p(\Omega_1)} + \|\vec{u}\|_{W_p^{2-1/p}(S_1)} + \|\vec{H}^{(1)}\|_{L_p(\Omega_1)} \right] \\ &\leq c \left( \|\text{rot} \vec{j}\|_{L_p(\Omega_1)} + \|\vec{H}^{(1)}\|_{L_p(\Omega_1)} \right). \end{aligned}$$

Furthermore, we obtain (9) for  $\varphi(x)$  the following inequality

$$\|\nabla \varphi\|_{W_p^2(\Omega_1)} \leq c \|\vec{H}^{(1)}\|_{W_p^2(\Omega_1)},$$

and hence

$$\|\vec{H}^{(2)}\|_{W_p^2(\Omega_1)} \leq c \|\vec{H}^{(1)}\|_{W_p^2(\Omega_1)}.$$

Next, we use the interpolation inequality [4]

$$\|\text{rot} \vec{H}^{(1)}\|_{L_p(S_1)} \leq \varepsilon \|D^2 \vec{H}^{(1)}\|_{L_p(\Omega_1)} + c(\varepsilon) \|\vec{H}^{(1)}\|_{L_p}.$$

Combining these inequalities, we obtain the estimate

$$\sum_{i=1}^2 \|\vec{H}^{(i)}\|_{W_p^2(\Omega_i)} \leq c(\Omega_i) (\|\text{rot} \vec{j}\|_{L_p(\Omega_1)} + \|\vec{j}(x)\|_{L_p(\Omega_1)}). \quad (17)$$

Using (17) from system (1), we get the estimate

$$\sum_{i=1}^2 \|\vec{E}^{(i)}(x)\|_{W_p(\Omega_i)} \leq c [\|\text{rot} \vec{H}\|_{W_p^1(\Omega_1)} + \|\vec{j}(x)\|_{W_p^1(\Omega_1)}] \leq c \left( \sum_{i=1}^2 \|\vec{H}^{(i)}\|_{W_p^1(\Omega_i)} \right). \quad (18)$$

for the vector field  $\vec{E}(x)$ . Thus, we have proved the following theorem.

**Theorem 2.** *If in (12) vectors  $\vec{j}(x), \text{rot} \vec{j}(x) \in L_p(\Omega_1)$ , then the electric and magnetic fields  $\vec{E}(x) \in W_p^1(\Omega_i)$  and  $\vec{H}(x) \in W_p^2(\Omega_i)$ ,  $i = 1, 2$ , and the estimates (17) and (18) hold.*

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